

An Efficient and Robust
Eigenvalue Method
for Small-Signal Stability
Assessment in Parallel
Processing

Jorge M. Campagnolo
COPPE/UFRJ

Nelson Martins
CEPEL

Djalma M. Falcão
COPPE/UFRJ

Rio de Janeiro - BRAZIL

Parallel Processing in Small-Signal Stability Analysis and Control

Methodology:

- Partial Eigensolution of Large Matrices

On-line and Off-line Applications:

- Electromechanical Stability
- Voltage Stability

Parallel Processing ...

- Algorithms for Partial Eigensolution are Parallelizable
- Parallel Computers are Available
- Only way to achieve required speed at reasonable cost

Results

Test System : $\left\{ \begin{array}{l} 6000 \text{ equations} \\ 1200 \text{ state variables} \end{array} \right.$

Computer : *iPSC/860* $\left\{ \begin{array}{l} 1 \text{ node} \\ 4 \text{ nodes} \\ 8 \text{ nodes} \end{array} \right.$

Algorithms Utilized : $\left\{ \begin{array}{l} \textit{Lop - sided Simul-} \\ \textit{taneous Iteration} \\ \textit{Bi - Iteration} \\ \textit{Hybrid} \end{array} \right.$

Algorithms Utilized

Lop-sided Simultaneous Iteration (LSSI)

- Sequential code available
- Parallel code reported in [1]

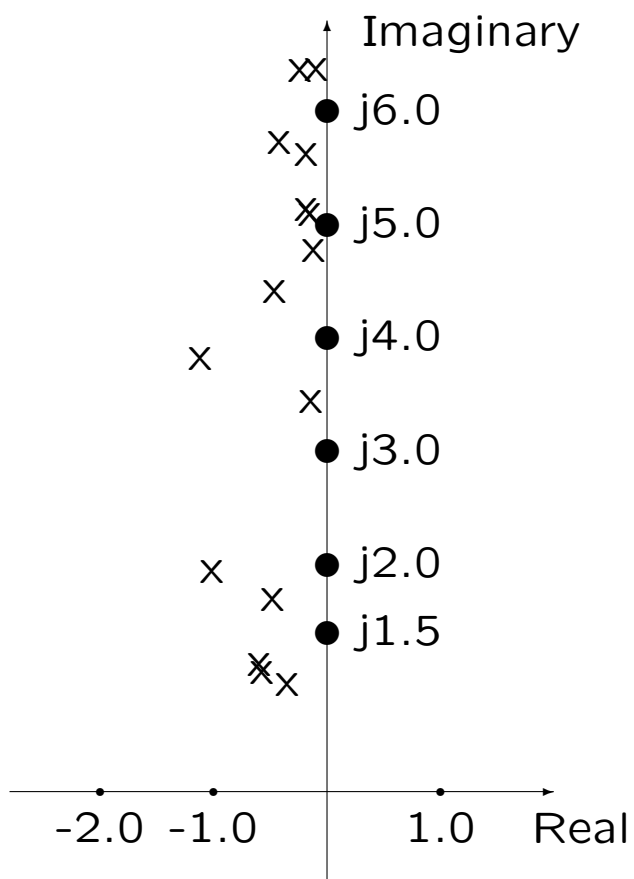
Bi-Iteration Algorithm (BI)

- Developed for non-symmetric matrices
- Obtains both right and left eigenvectors
- Quadratic convergence rate for eigenvalues
- Linear convergence rate for eigenvectors
- Requires more computational effort and memory space than LSSI

Hybrid Algorithm

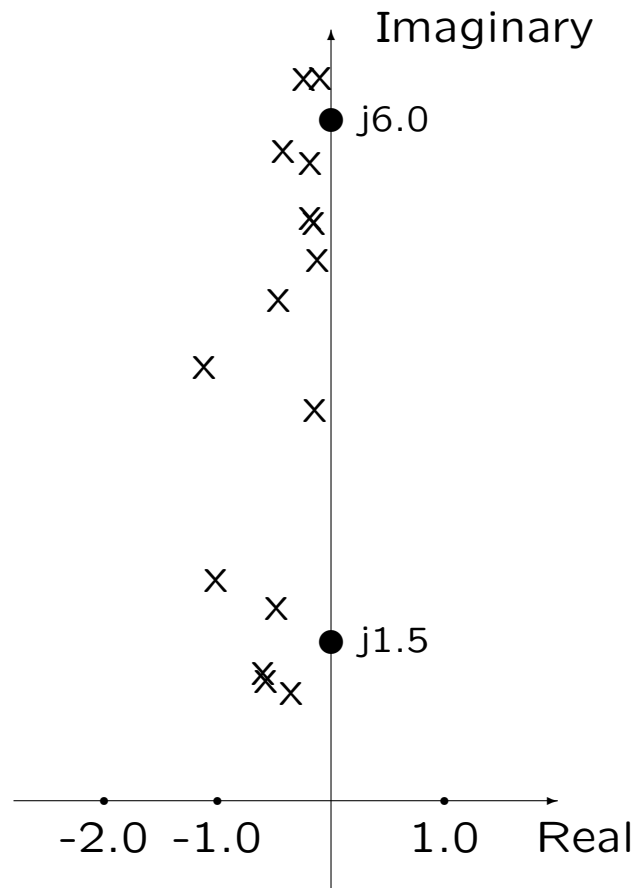
- Combination of two methods
 - Bi-iteration (1^{st} stage)
 - Inverse Iteration (2^{nd} stage)
- Specially suited for parallel processing
- Excellent performance in sequential processing

Location of System Eigenvalues and Shifts



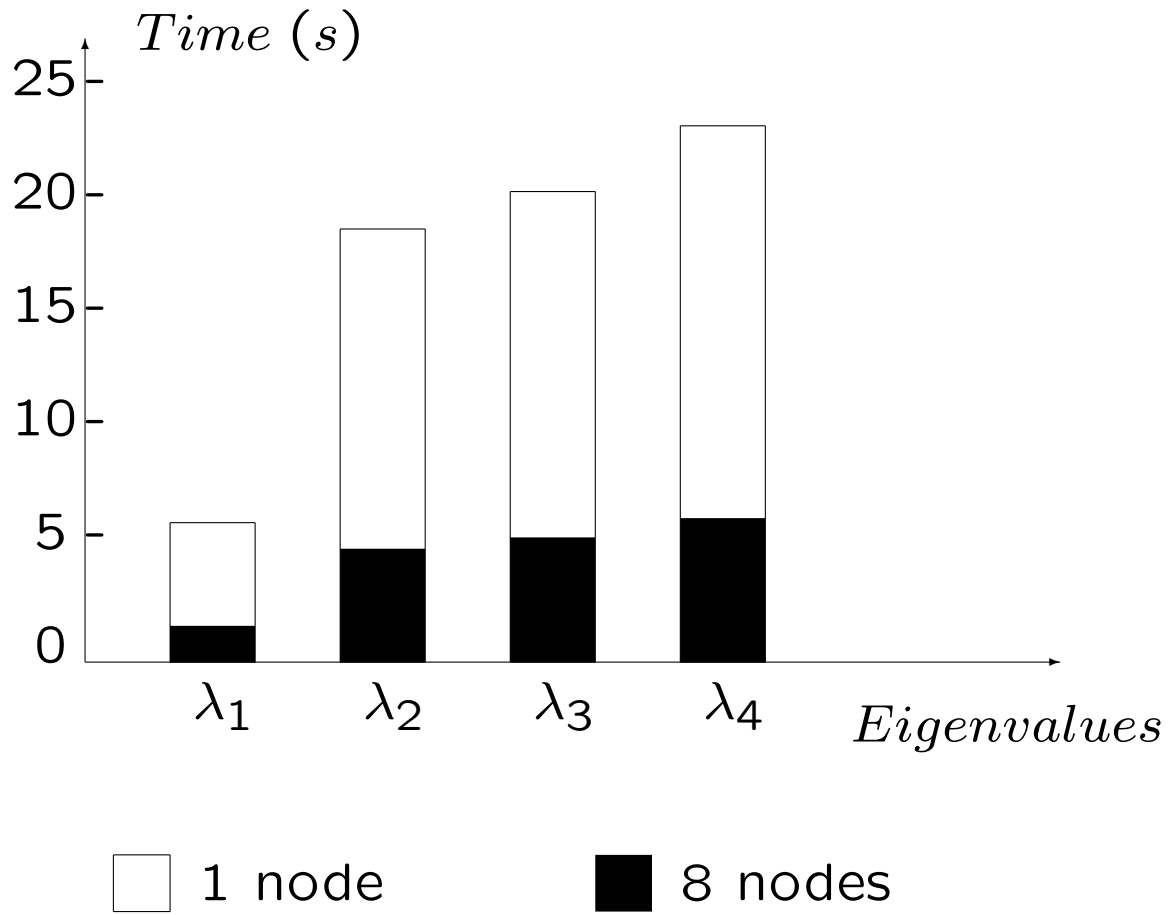
- – complex shifts
- x – converged eigenvalues

Eigenvalue Convergence for Different Shifts



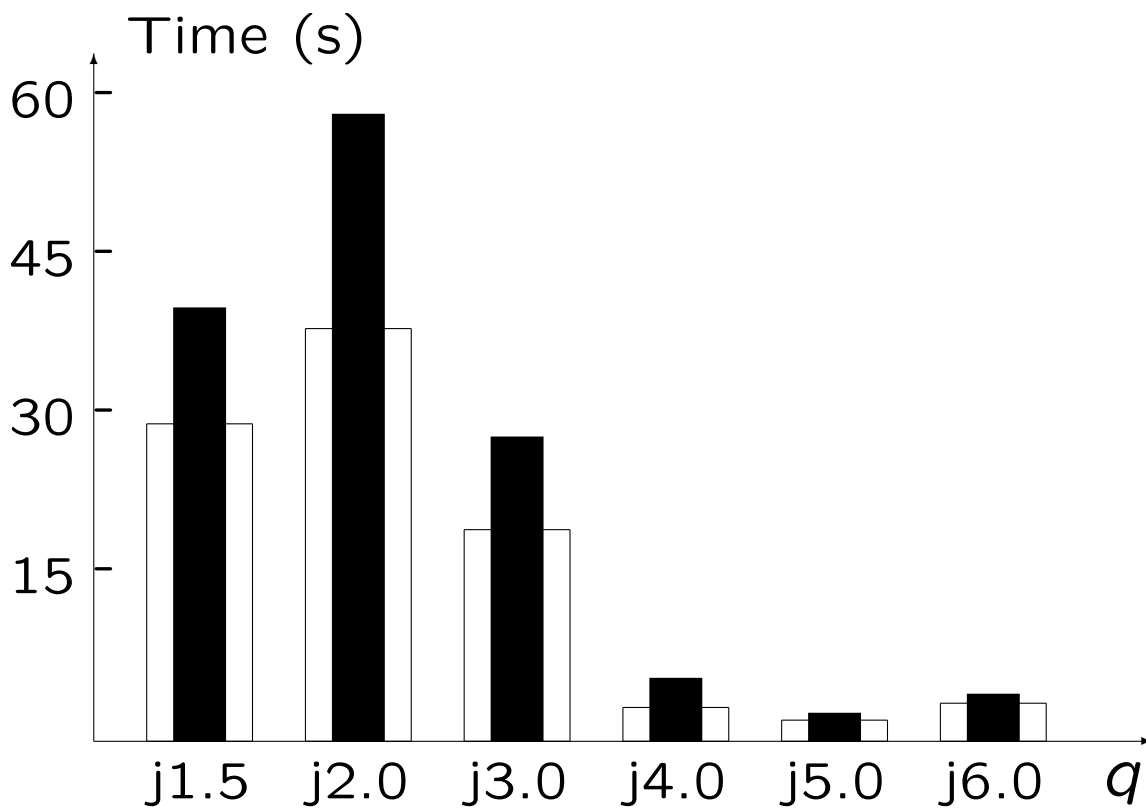
● – complex shifts
x – eigenvalues

LSSI Computation Time



(8 trial vectors and $K_f = 3$)

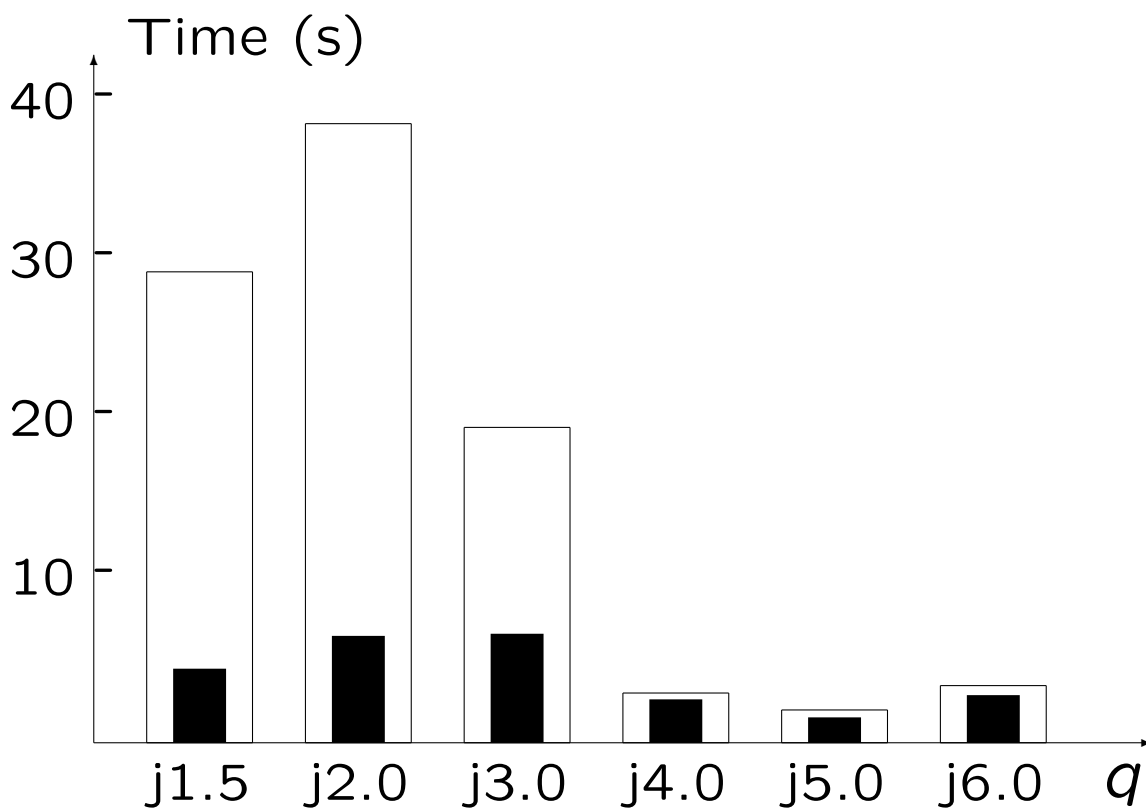
Computation Times for Parallel LSSI and Parallel BI Algorithms



■ - BI q - *complex shift*
□ - LSSI

(Convergence for 3 eigenvectors out of 4 trial vectors)

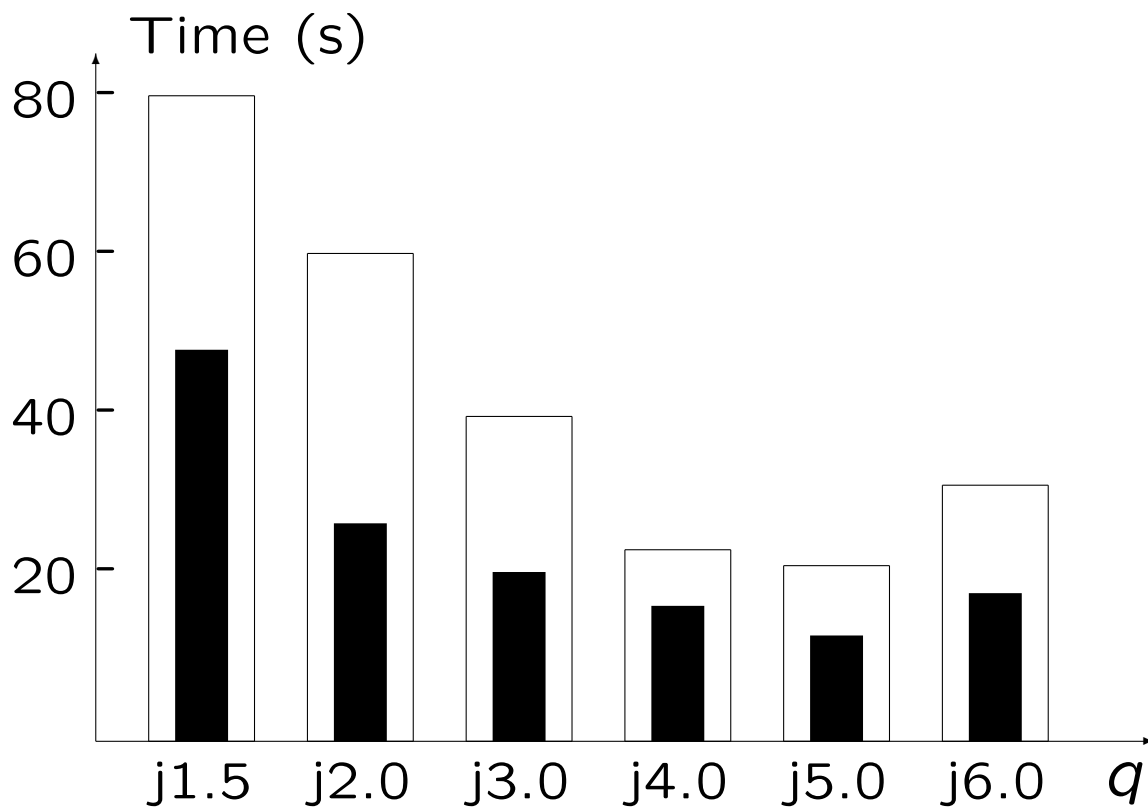
Computation Times for Parallel Hybrid and Parallel LSSI Algorithms



■ - Hybrid q - *complex shift*
□ - LSSI

(Convergence for 3 eigenvectors out of 4 trial vectors)

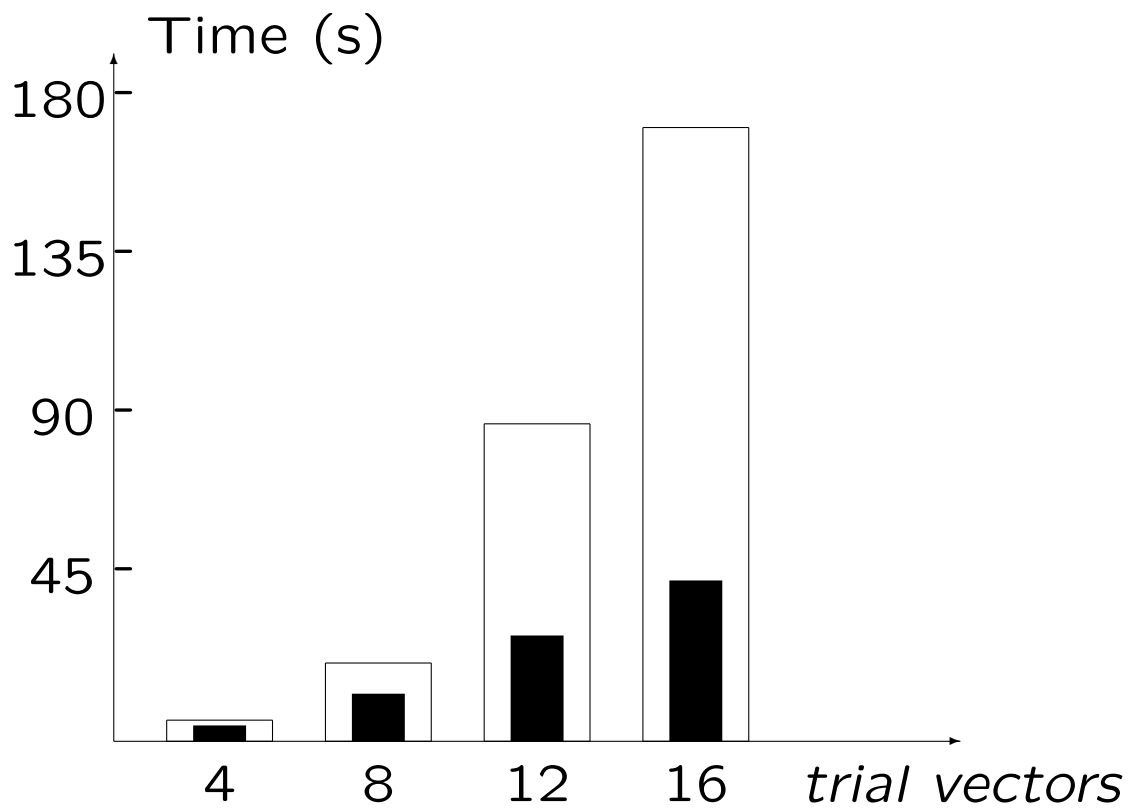
Comparative Results in Sequential Computation



■ - Hybrid q - *complex shift*
□ - LSSI

(Convergence for 6 eigenvectors out of 8 trial vectors)

Comparative Results in Sequential Computation



■ - Hybrid
□ - LSSI

(25 % of Guard Vectors)

Power System Parallel Eigensolutions

- Hybrid algorithm, a simple but definite evolution
- A revolutionary method will soon be published

Location of System Eigenvalues

