

# 2002 IEEE/PES Winter Meeting

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## ADVERSE IMPACTS ON VOLTAGE AND REACTIVE POWER PERFORMANCES DUE TO PSSs

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## INTRODUCTION

- **Studying the adverse terminal voltage and reactive power transients induced by the presence of PSSs**
  - **Comparing the PSSs derived from either rotor speed, terminal power or integral of accelerating power**
  - **Presenting some of the benefits introduced by the ramp-tracking fourth-order filter, for the  $PSS_{\int P_{acel}}$**

# STEP RESPONSE OF A SECOND ORDER SYSTEM

## ➤ Second order system with one zero

|   |   |
|---|---|
| $G(s) = \frac{\omega_n^2(as + 1)}{(s^2 + 2\zeta\omega_n s + \omega_n^2)}$ |   |
| <b>Zero</b>   | $s_z = -\frac{1}{a}$  |
| <b>Poles</b>  | $s_{p1}, s_{p2} = -\zeta\omega_n \pm j\omega_n\sqrt{1-\zeta^2}$ |

## ➤ The dynamical behavior of $G(s)$ will be assessed for different zero locations:

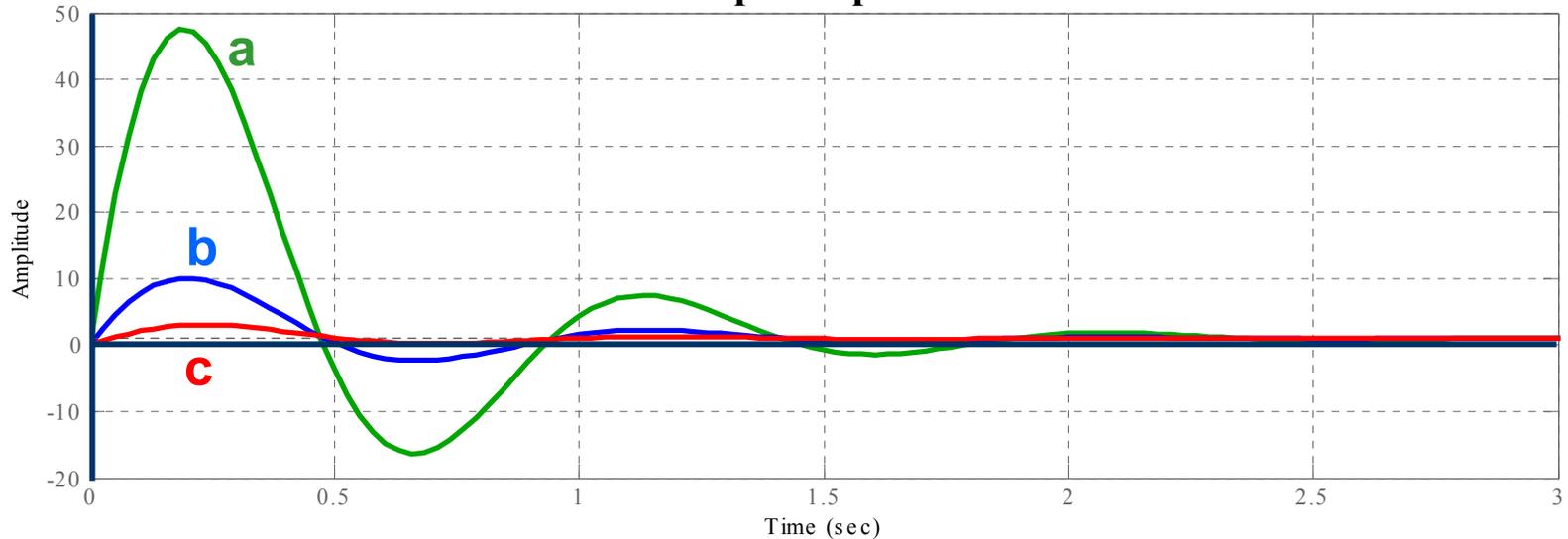
$$\mathbf{a \Rightarrow s_z = -0,1 + j0}$$

$$\mathbf{b \Rightarrow s_z = -0,5 + j0}$$

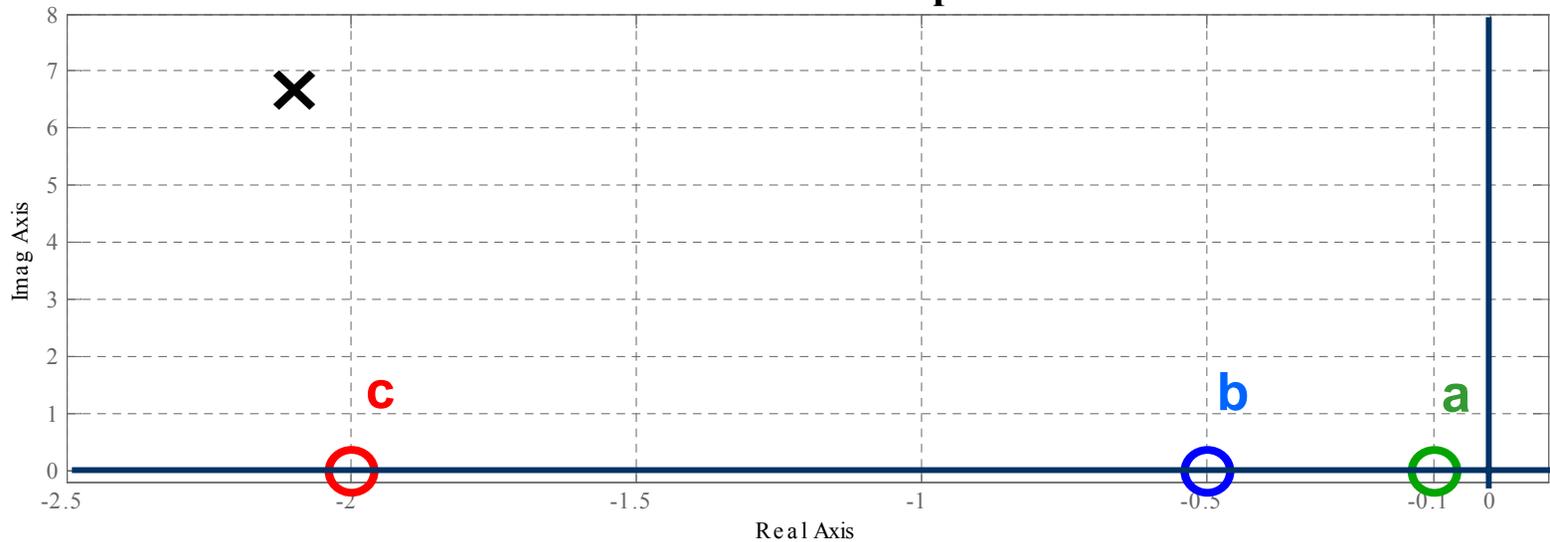
$$\mathbf{c \Rightarrow s_z = -2,0 + j0}$$

# STEP RESPONSE OF A SECOND ORDER SYSTEM

## Step Response



## Pole-Zero Map



## STEP RESPONSE OF A SECOND ORDER SYSTEM

- **Settling time and final value are not affected by the zero location.**
- **Overshoot is greatly affected by the proximity of the zero to the origin.**
- **Knowledge of the zero locations for selected transfer functions may help designing better controllers**

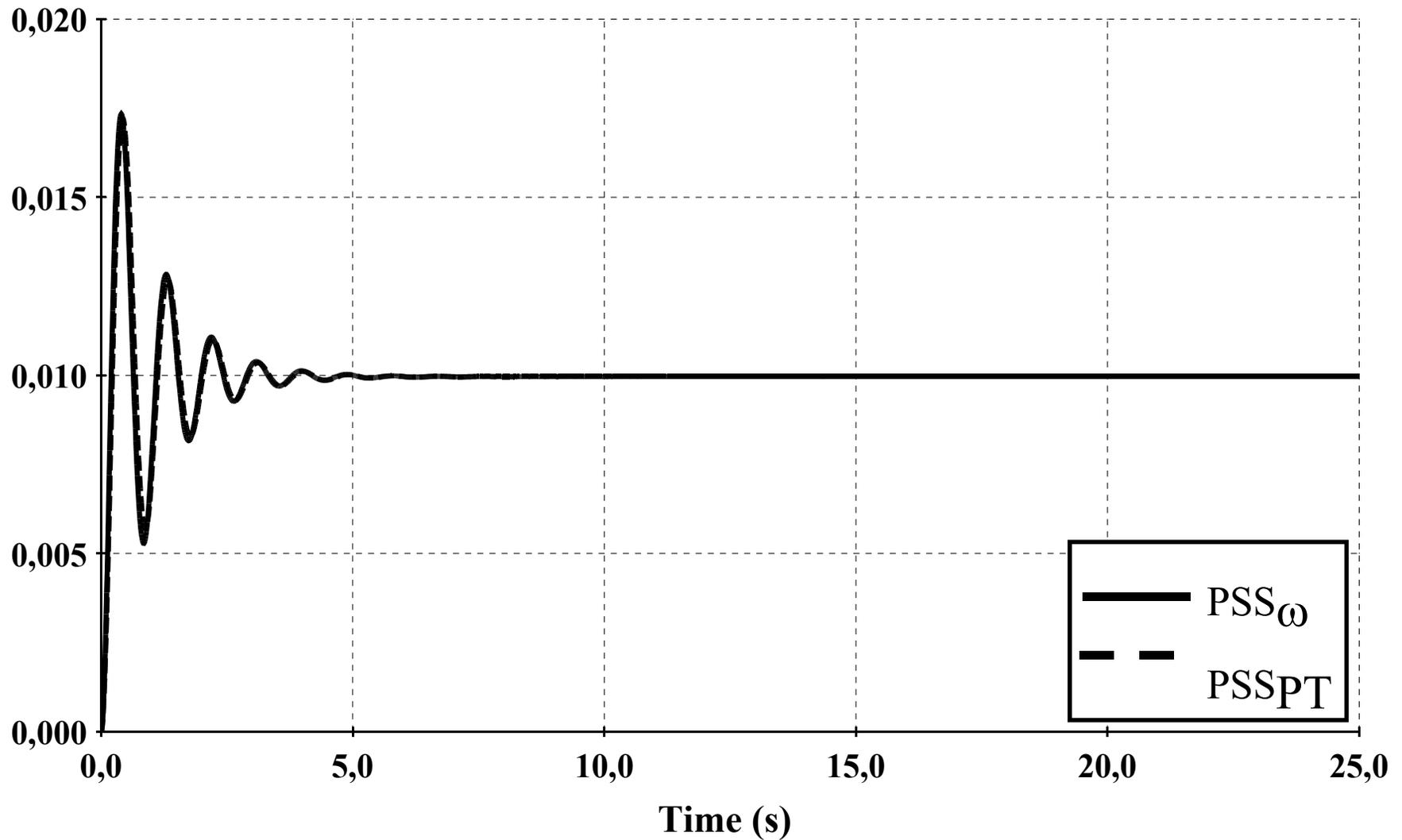
# PERFORMANCE OF A SMIB SYSTEM EQUIPPED WITH PSS

- **Comparison of generator terminal transients for:**
  - **Different PSS input signals:  $PSS_{\omega}$ ,  $PSS_{PT}$ ,  $PSS_{\int P_{acel}}$**
  - **$PSS_{\int P_{acel}}$  with and without ramp tracking filter**
  
- **Models and parameters of generator, AVR and PSS are those of the Xingó power plant (a 3000 MW hydro plant owned by CHESF, in Brazil)**

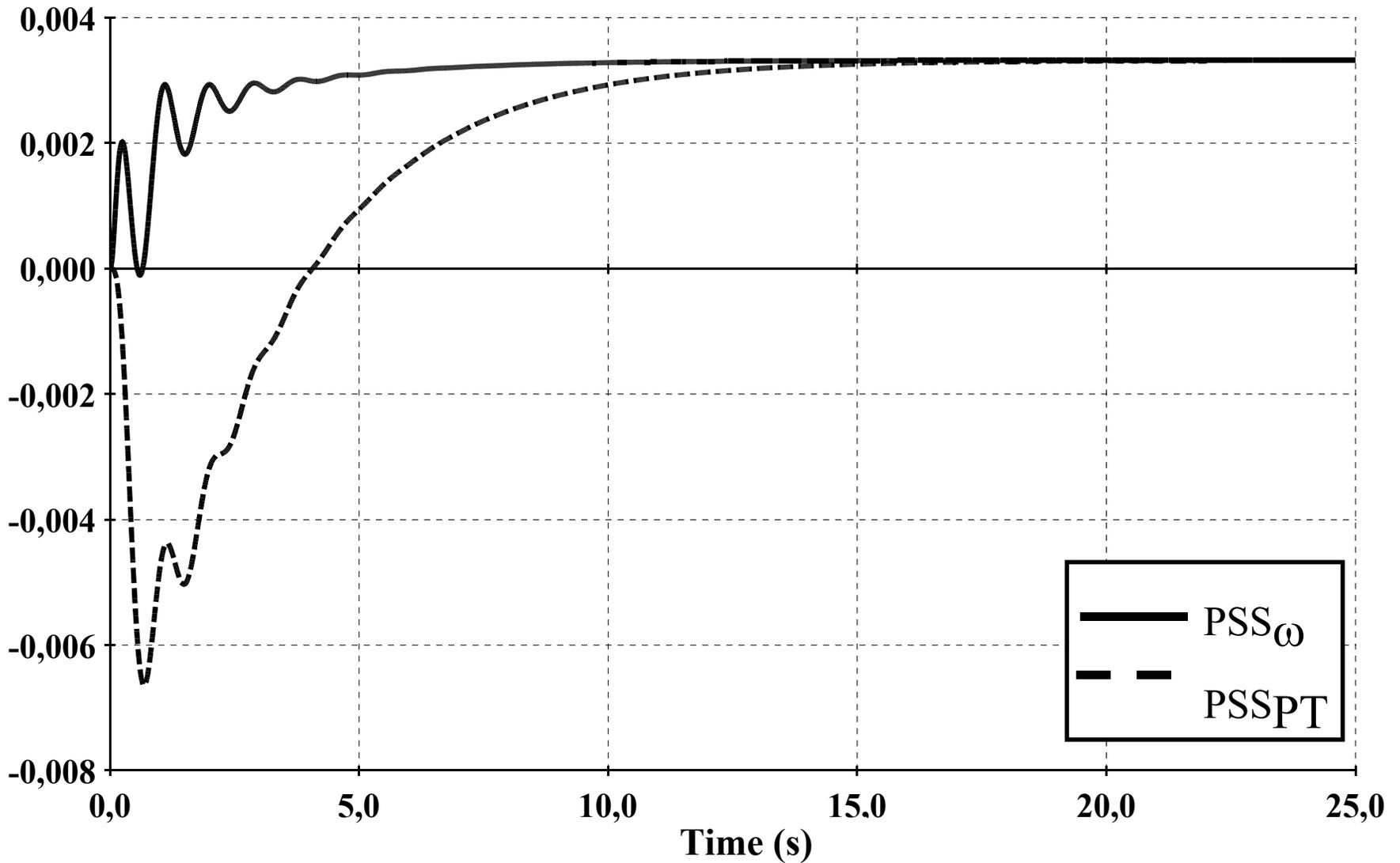
## PSS DERIVED FROM ROTOR SPEED OR TERMINAL POWER

- The two PSSs were tuned so that the electromechanical mode is the same in both cases
  - A fair comparison among PSSs may therefore be made
- The applied disturbance is a 1 % step change in  $P_{MEC}$
- The monitored system variables are generator terminal voltage, active and reactive power
- Pole-zero maps for  $(\Delta P_T / \Delta P_{MEC})$  and  $(\Delta Q_T / \Delta P_{MEC})$

# ACTIVE POWER CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

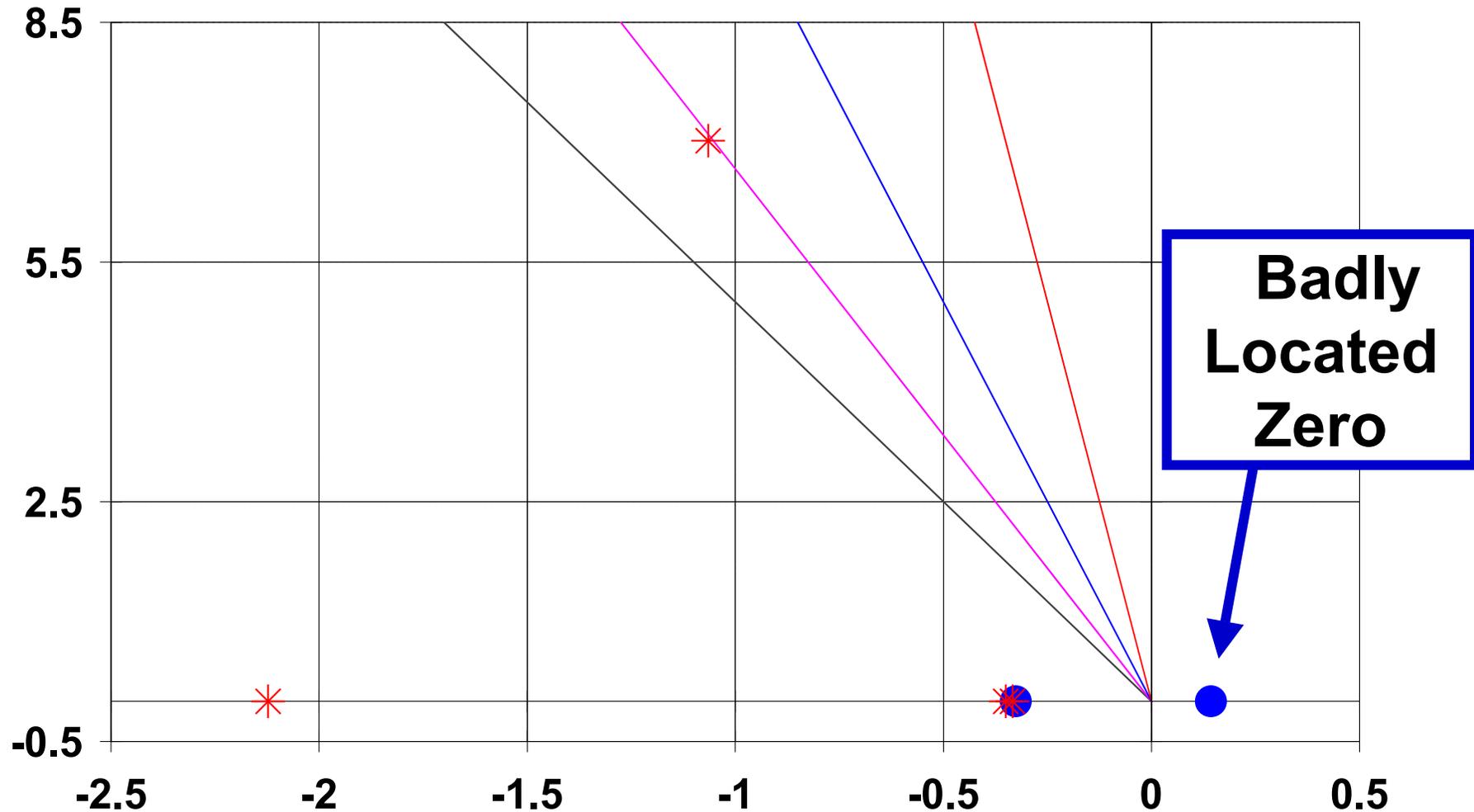


# REACTIVE POWER CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

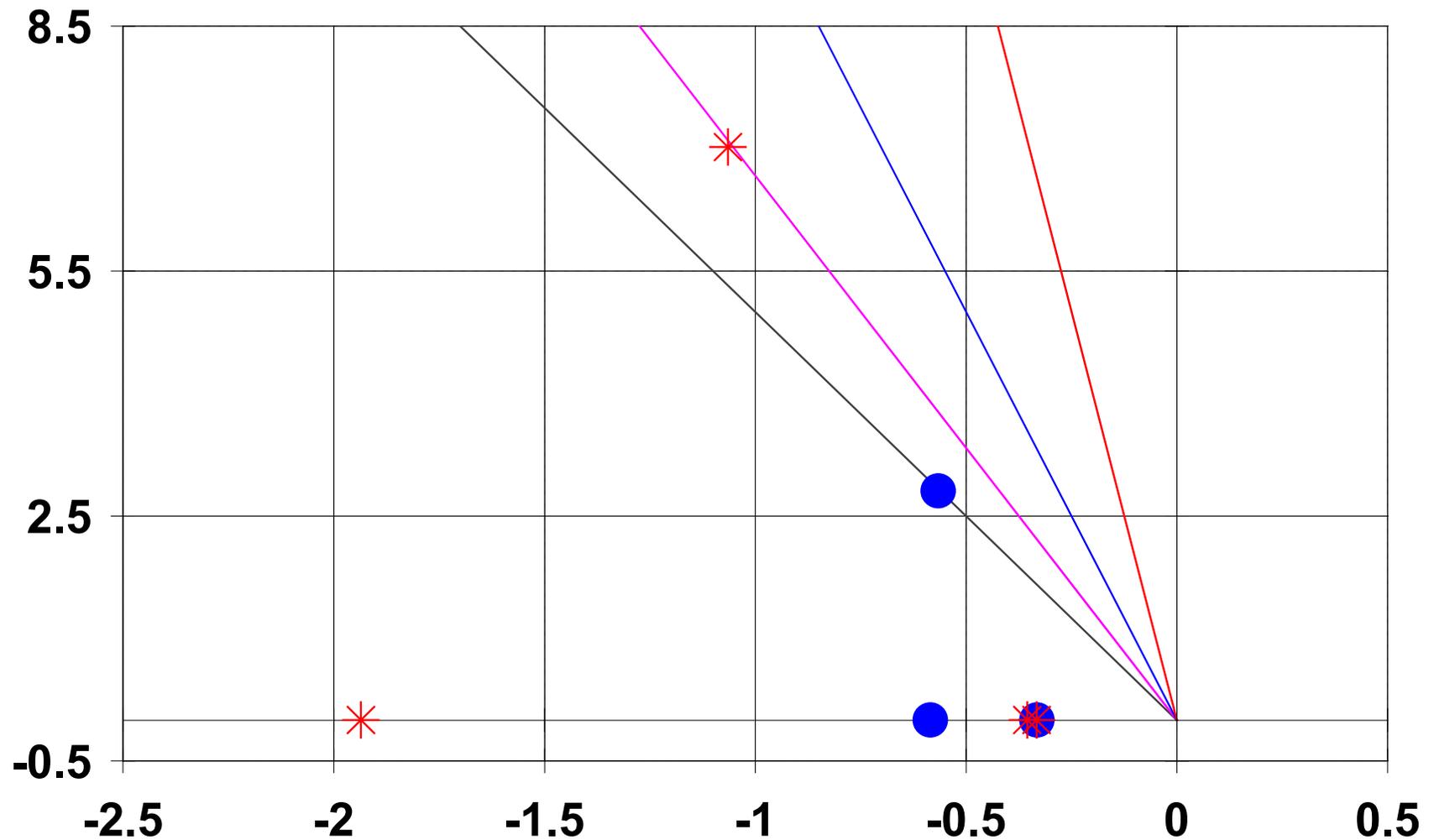


# POLE-ZERO MAP FOR $\Delta Q_T / \Delta P_{MEC}$ (PSSPT)

- Zero near the origin causes bigger overshoot in the step response



# POLE-ZERO MAP FOR $\Delta Q_T / \Delta P_{MEC}$ ( $PSS\omega$ )

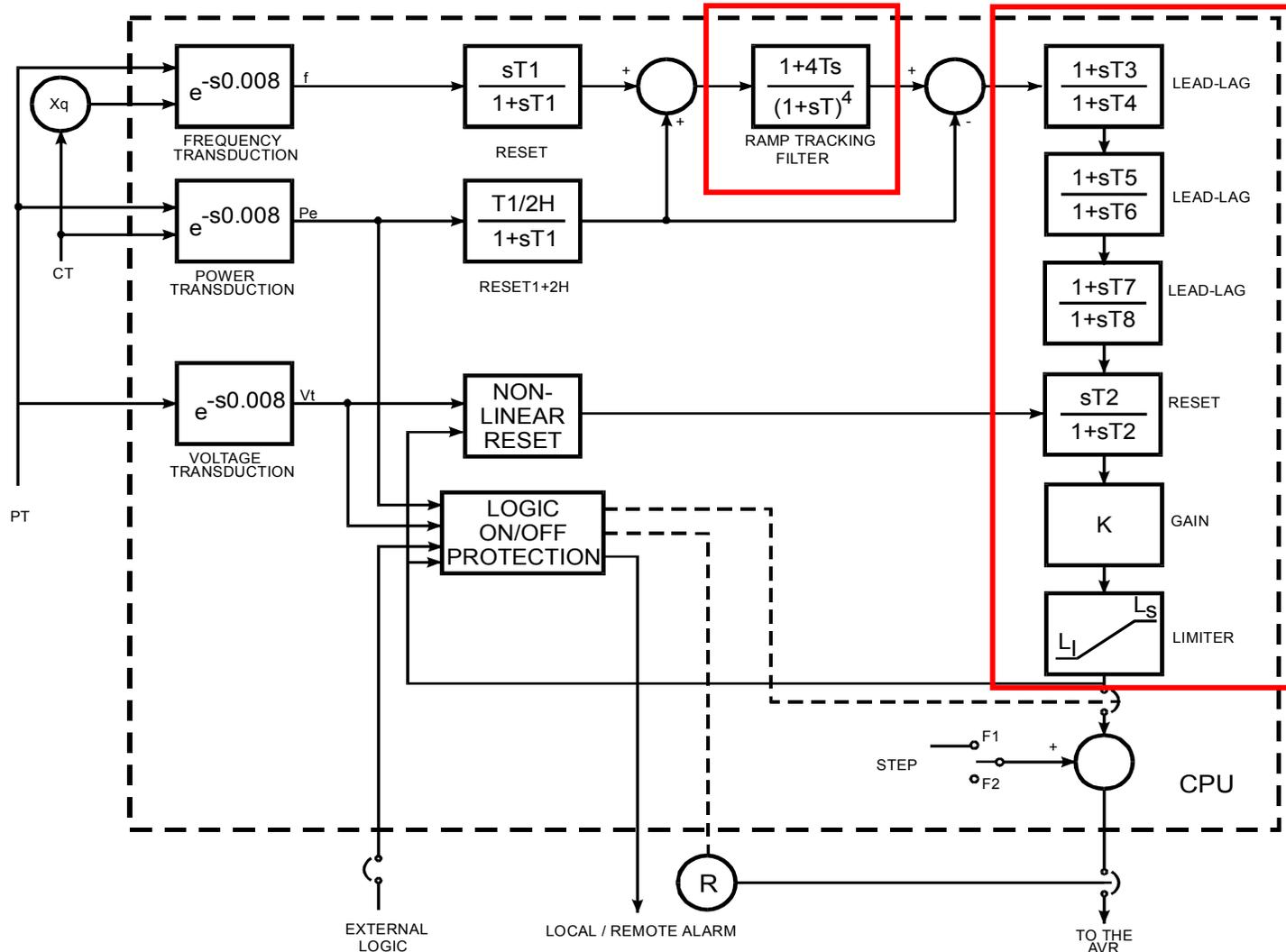


## **PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER**

- **Preferred PSS structure in Brazil and abroad**
  - **Embedded fourth order ramp tracking filter**
  - **Effective input signal is close to filtered rotor speed**
  - **The PSSs installed at Xingó are of this type**

# PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER

## Power System Stabilizer – REIVAX PWX 500



## PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER

- **Analysis of the pole-zero map for  $(\Delta Q_T/\Delta P_{MEC})$**
  
- **Time response to a 1 % step change in  $P_{MEC}$**
  
- **Assessment of PSS performance**
  - ➔ **With or without fourth-order ramp tracking filter**
  - ➔ **Different filter configurations**
    - **Filter with ramp tracking (different time constants)**
    - **Filter without ramp tracking**

# PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER

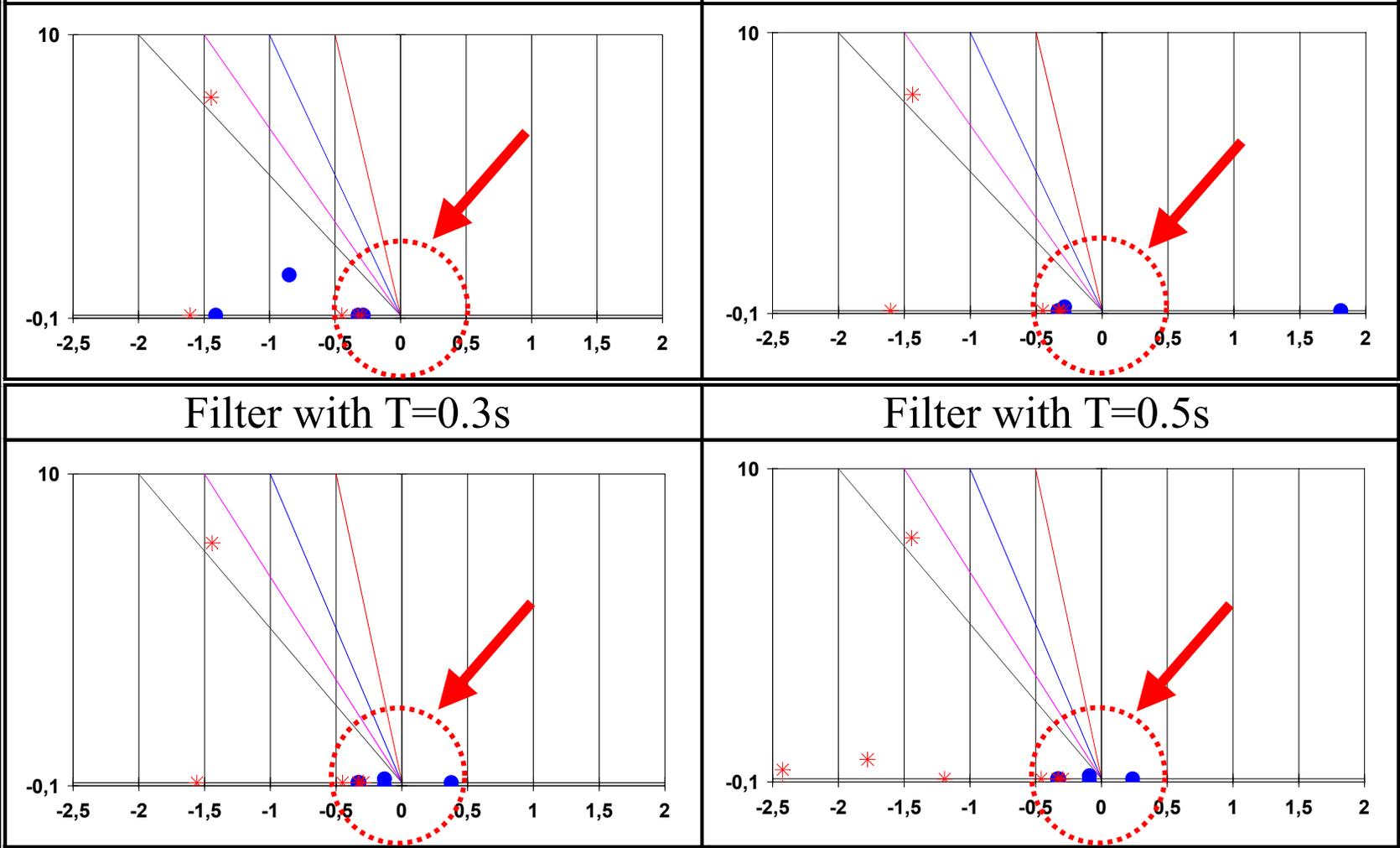
## Pole-Zero Map for $(\Delta Q_T/\Delta P_{MEC})$

### Without Filter

### Filter with T=0.1s

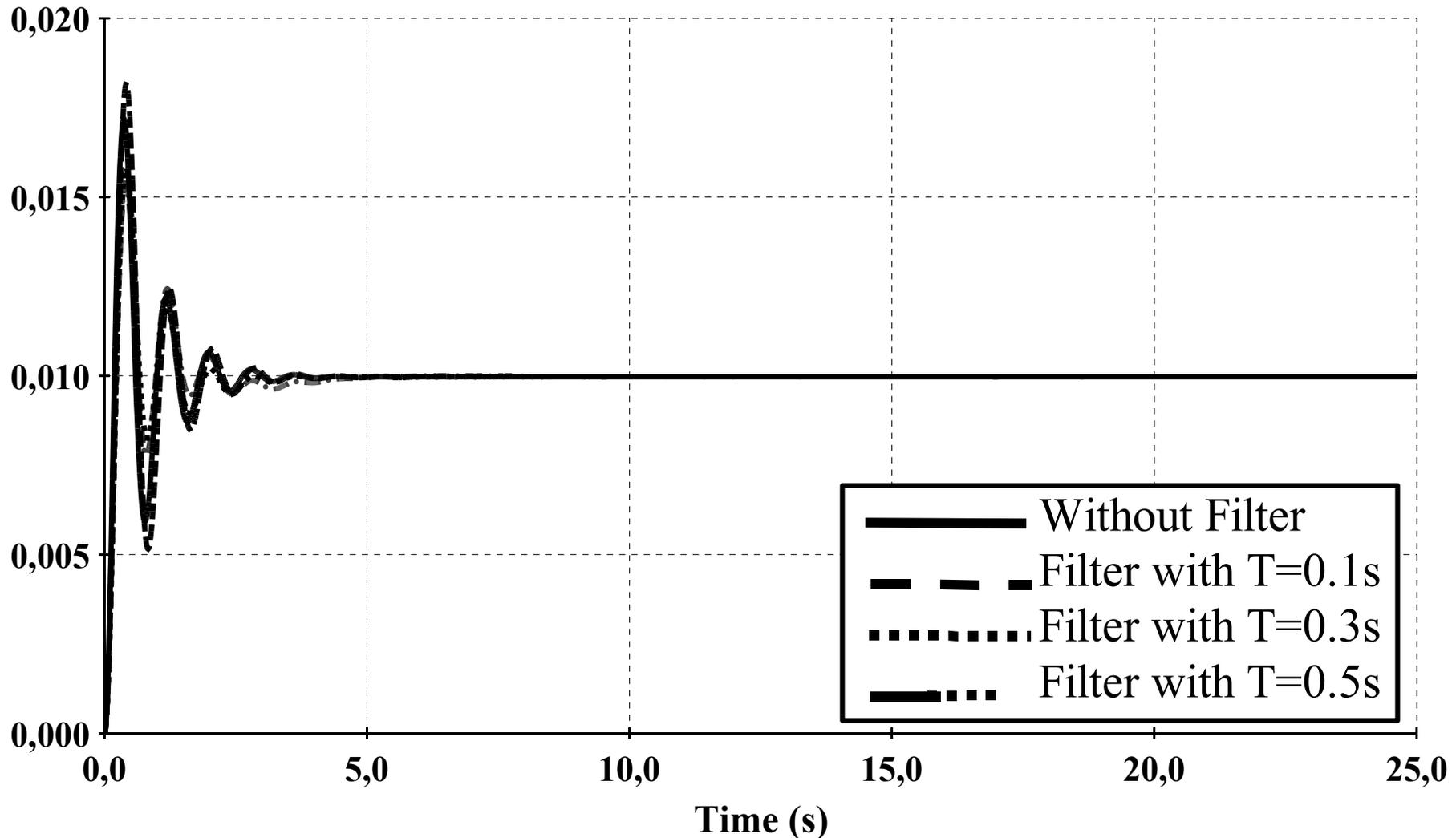
### Filter with T=0.3s

### Filter with T=0.5s



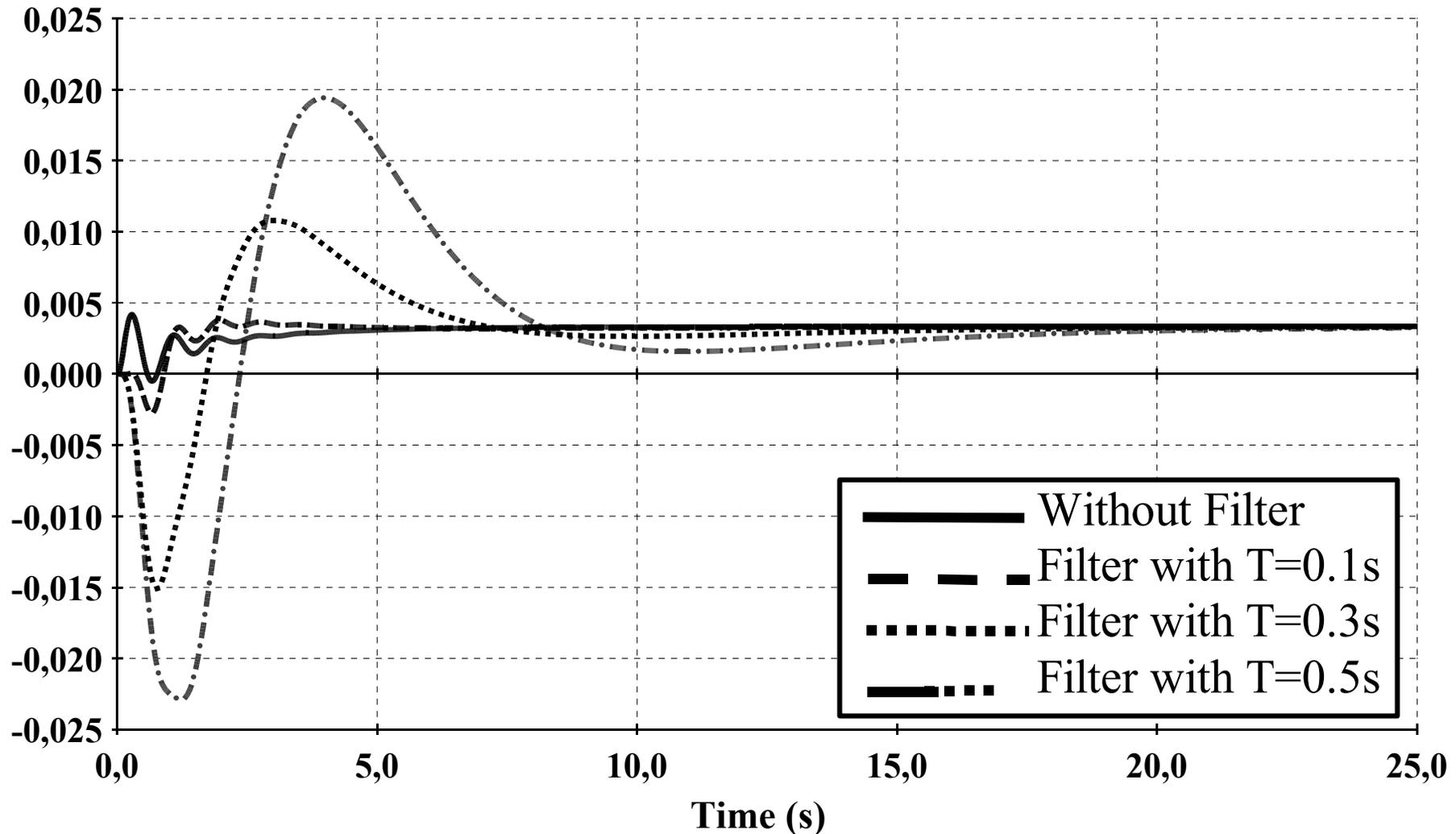
# ACTIVE POWER CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

➤ PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER



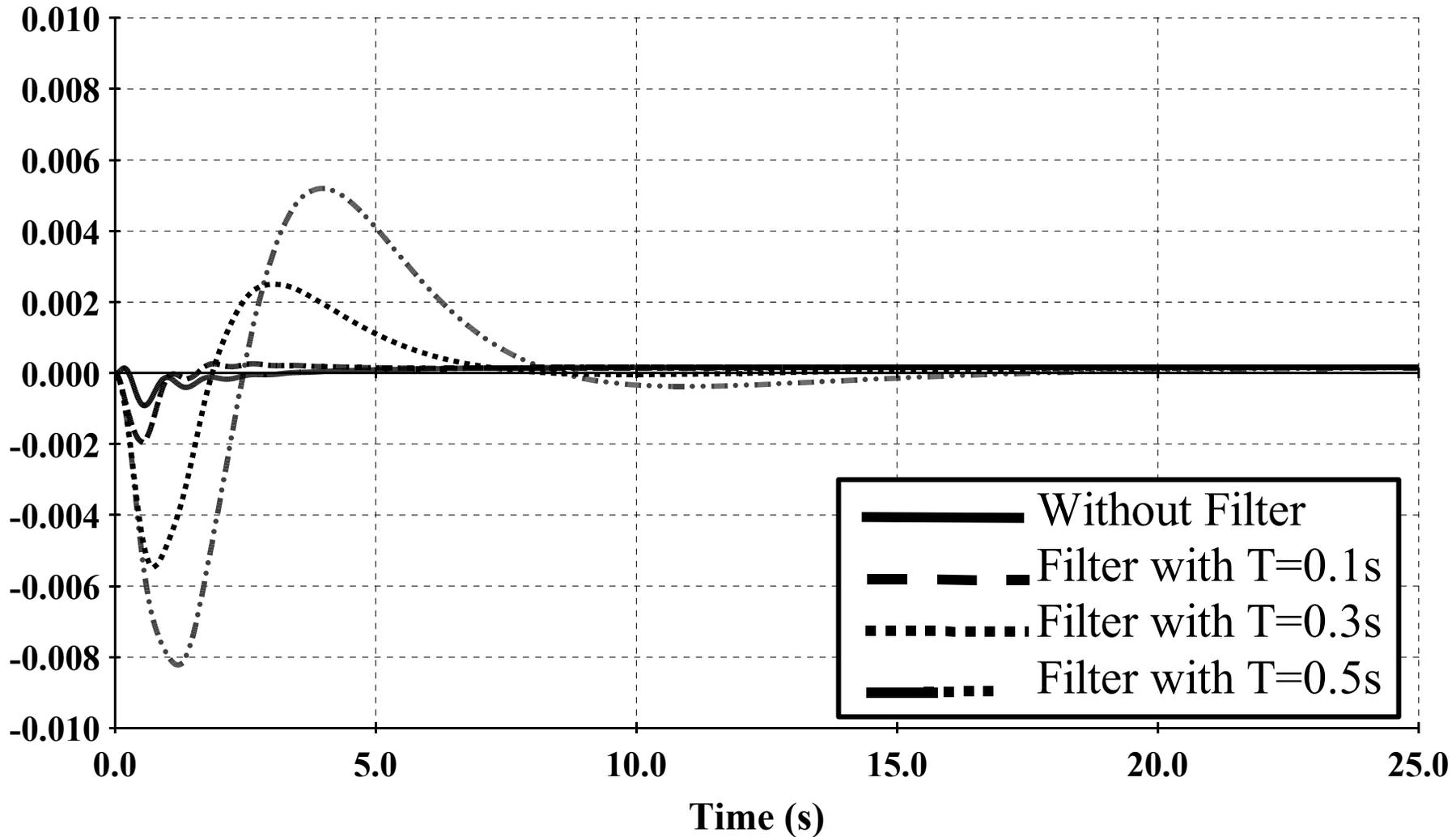
# REACTIVE POWER CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

## ➤ PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER



# TERMINAL VOLTAGE CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

## ➤ PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER

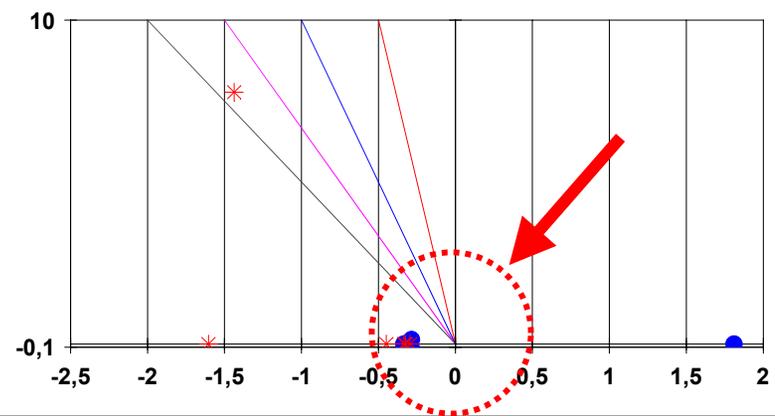
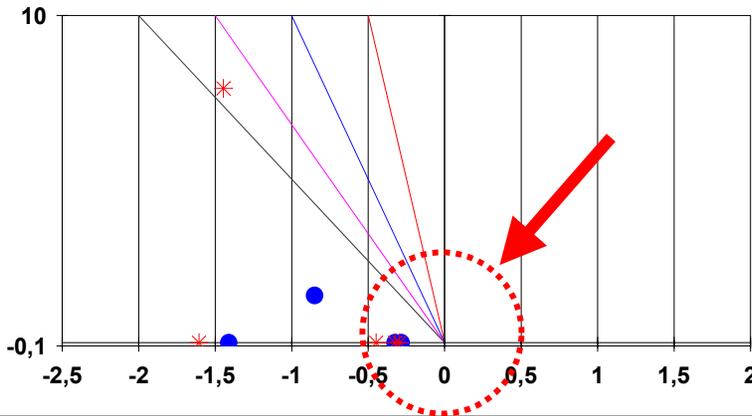


# PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER

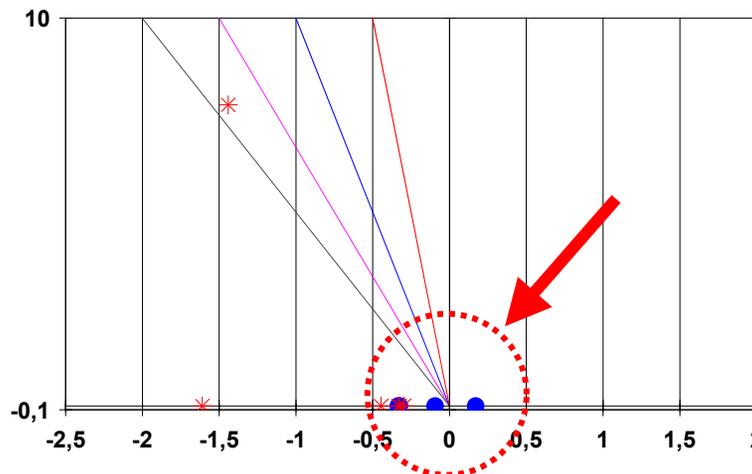
## Pole-Zero Map for $(\Delta Q_T / \Delta P_{MEC})$

Without Filter

Filter with  $T=0.1s$

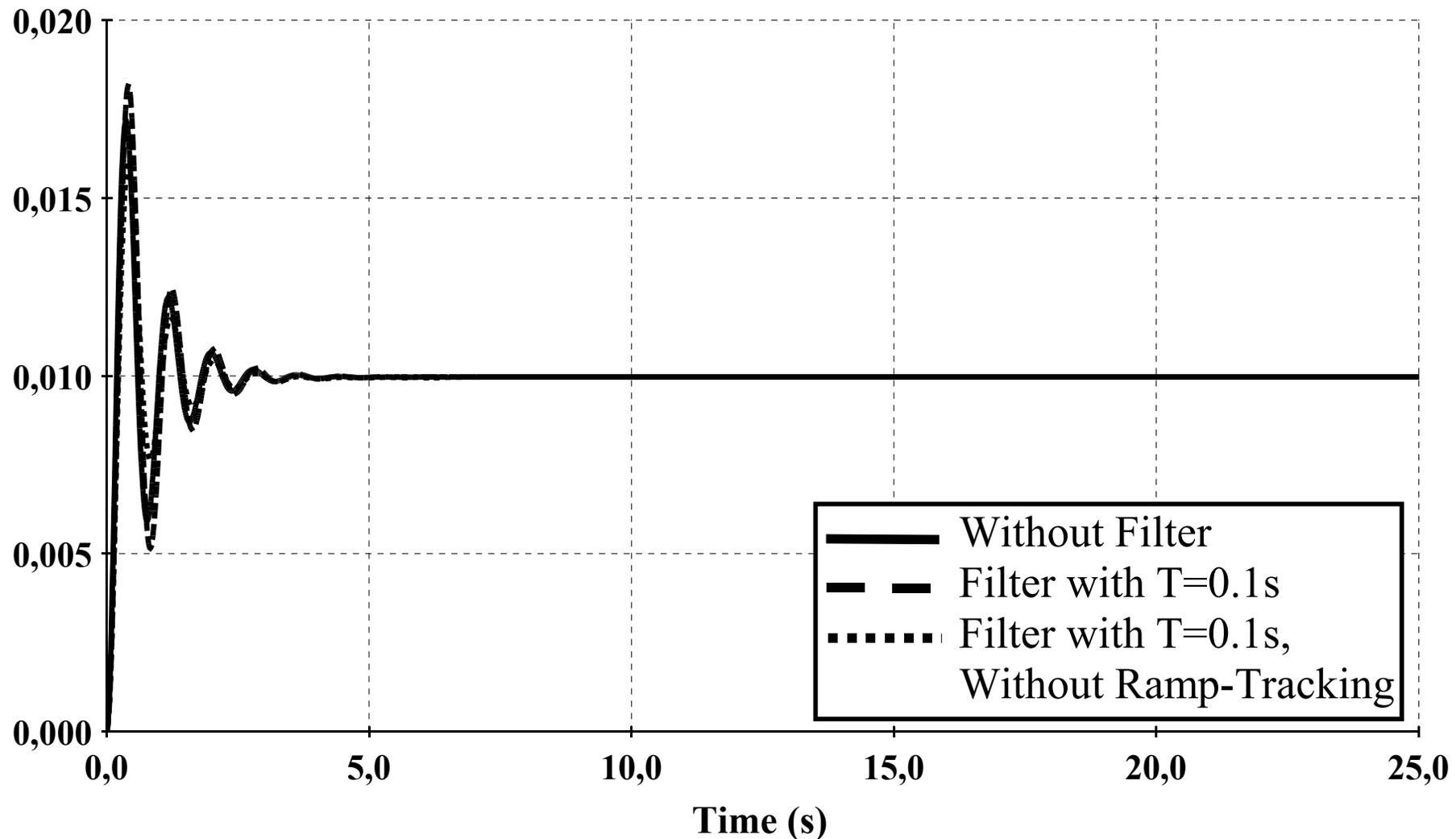


Filter with  $T=0.1s$ , without Ramp Tracking



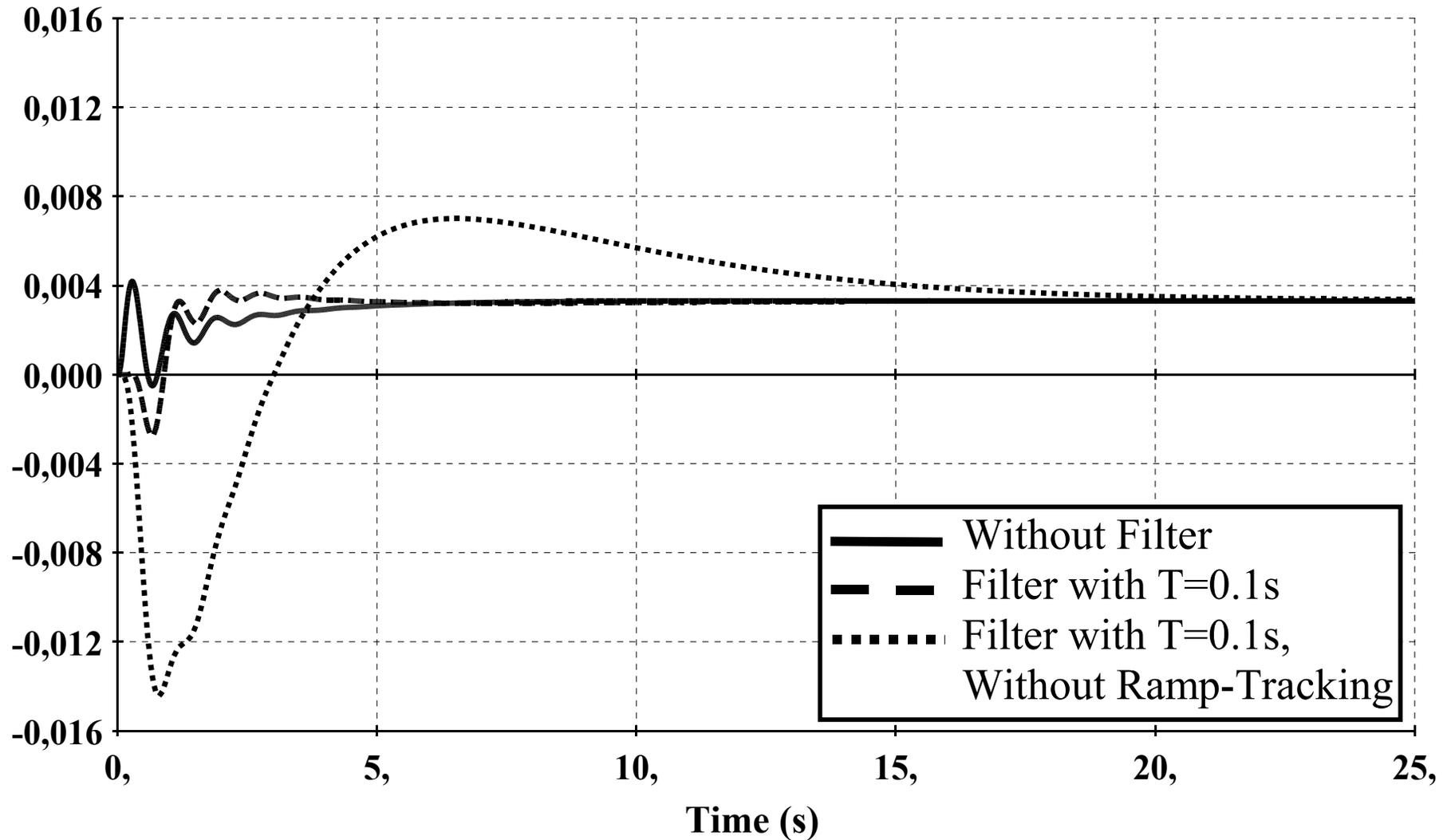
# ACTIVE POWER CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

## ➤ PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER



# REACTIVE POWER CHANGES FOLLOWING $\Delta P_{MEC}$ IN SMIB

## ➤ PSS DERIVED FROM INTEGRAL OF ACCELERATING POWER



## CONCLUSIONS

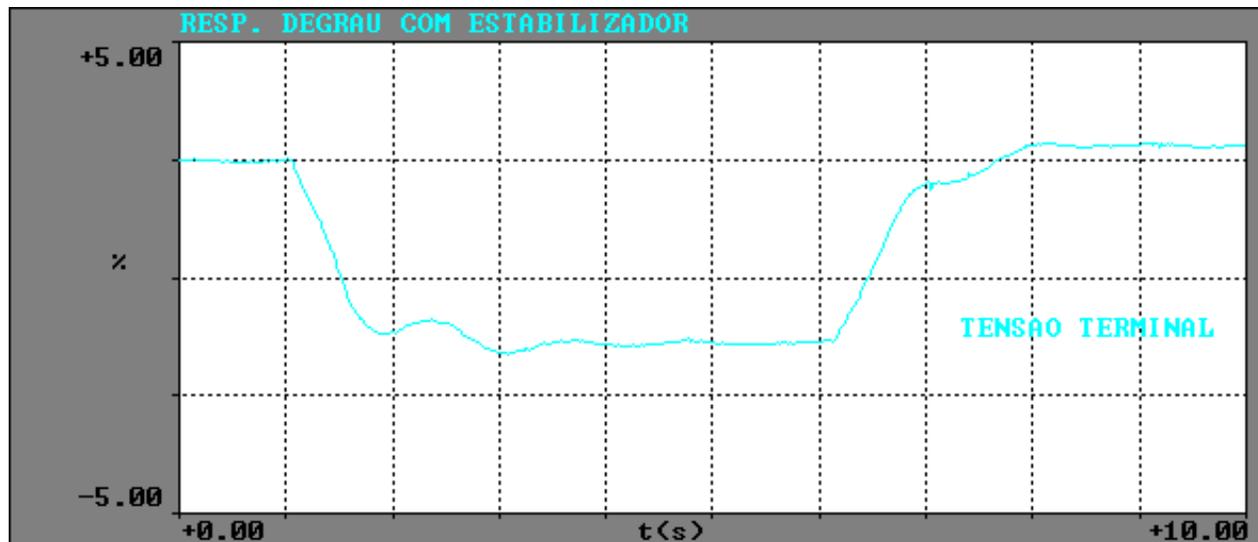
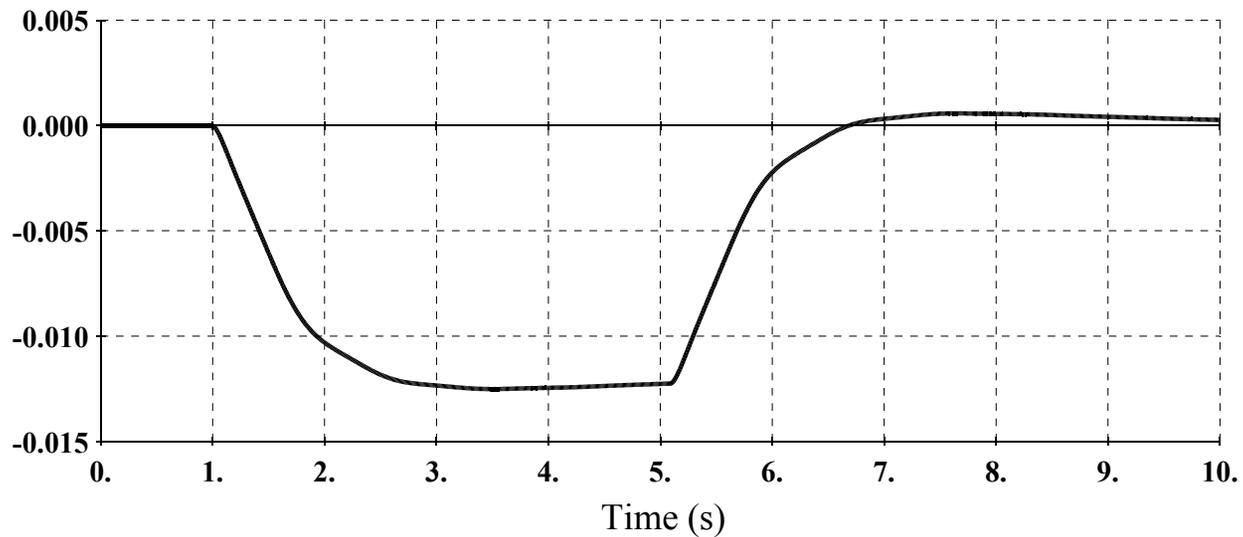
- **TF zeros proved to be a valuable in the study of adverse transients on terminal voltage and reactive power**
- **Different PSSs compared for a 1 % step change in  $P_{MEC}$** 
  - ➔ **Active power response  $\Rightarrow$  identical behavior**
  - ➔ **Voltage and reactive power response  $\Rightarrow$  very different transient response, showing large overshoots in some cases**
- **The studies confirmed the practical benefits of using the fourth-order ramp tracking filter in PSSs derived from integral of accelerating power**

## APPENDIX: COMPARING FIELD TESTS WITH SIMULATIONS

- **Tests carried out during the commissioning of the PSSs at the Xingó power plant**
  
- **Negative step at voltage reference during 4 s**

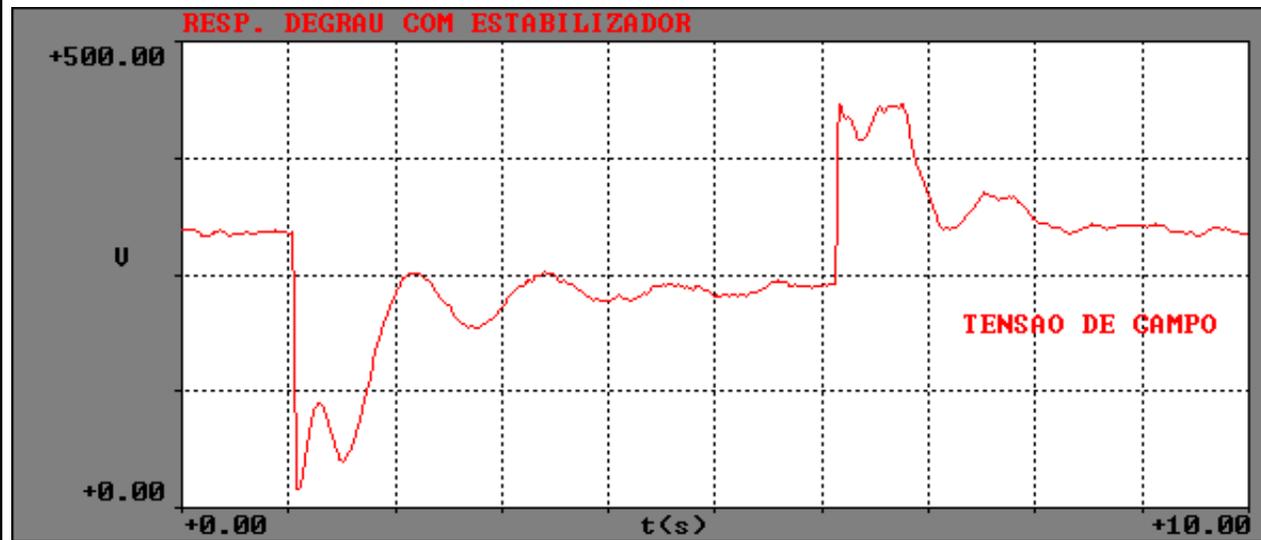
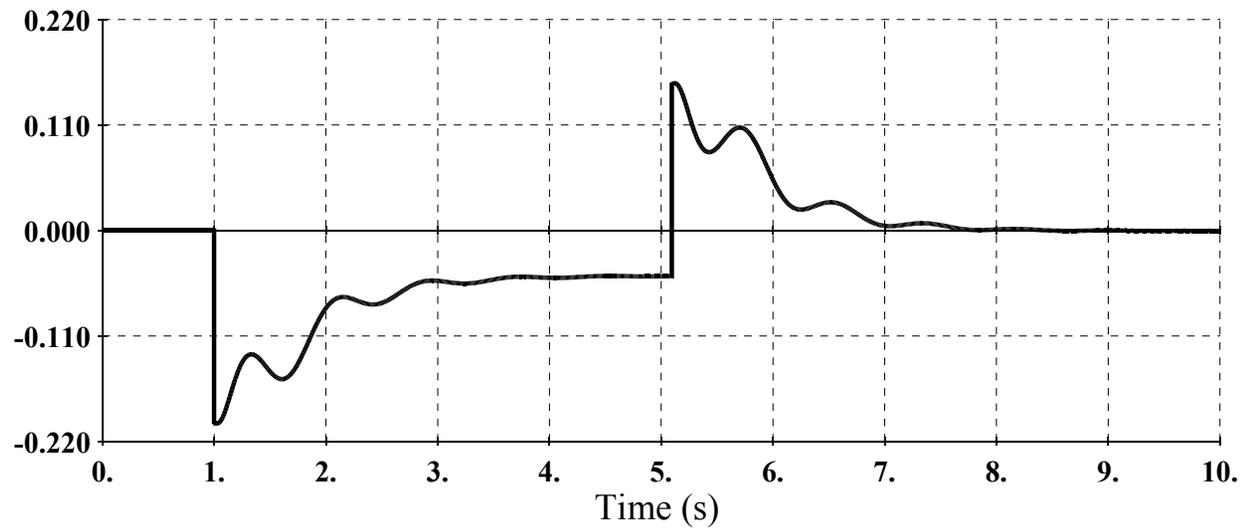
# APPENDIX: COMPARING FIELD TESTS WITH SIMULATIONS

**Terminal  
Voltage**



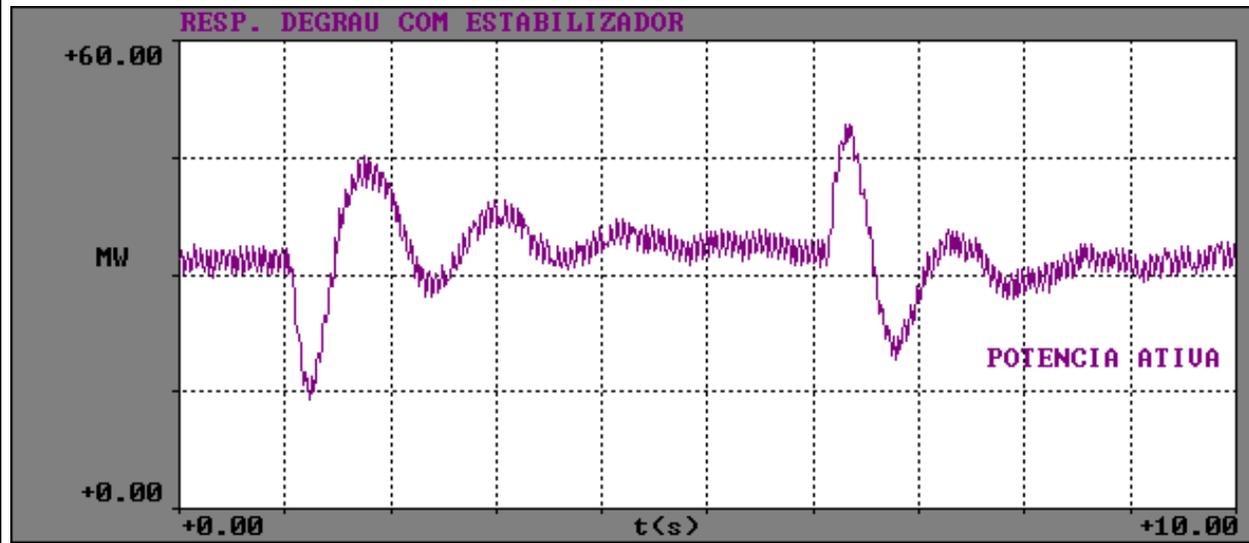
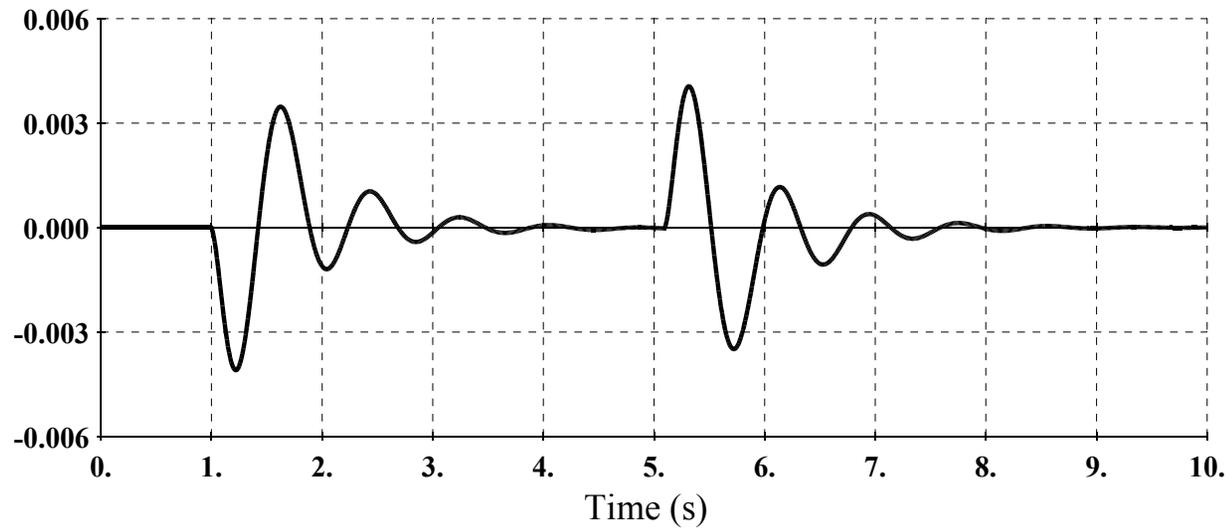
# APPENDIX: COMPARING FIELD TESTS WITH SIMULATIONS

Field  
Voltage



# APPENDIX: COMPARING FIELD TESTS WITH SIMULATIONS

**Terminal  
Active  
Power**



# APPENDIX: COMPARING FIELD TESTS WITH SIMULATIONS

**Terminal  
Reactive  
Power**

